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NOTES

1.0 INTRODUCTION

The procedures contained in this manual include all the specifications, instructions, and graphics needed to diagnose engine control module (ECM) and sentry key immobilizer system (SKIS) problems; they are no start, diagnostic trouble code, and no trouble code problems for the ECM. The diagnostics in this manual are based on the trouble condition or symptom being present at the time of diagnosis.

When repairs are required, refer to the appropriate volume of the service manual for proper removal and repair procedure.

Diagnostic procedures change every year. New diagnostic systems may be added; carryover systems may be enhanced. IT IS RECOMMENDED THAT YOU REVIEW THE ENTIRE MANUAL TO BECOME FAMILIAR WITH ALL NEW AND CHANGED DIAGNOSTIC PROCEDURES.

This manual is designed to begin all diagnosis at the DTC TEST, which is located at the beginning of Section 7.1. This will cover all the necessary requirements to begin a logical diagnostic path for each problem. If there is a diagnostic trouble code (DTC) detected, it will direct you to the trouble code test. If there are no trouble codes present, it will direct you by symptom to a no-trouble code test.

This book reflects many suggested changes from readers of past issues. After using this book, if you have any comments or recommendations, please fill out the form at the back of the book and mail it back to us.

1.1 System Coverage

This diagnostic procedures manual covers all 1999 GS body equipped with the 2.5L VM diesel engine.

1.2 <u>Six-Step Troubleshooting Procedure</u>

Diagnosis of the engine control module (ECM) and SKIS is done in six basic steps:

- verification of complaint
- verification of any related symptoms
- symptom analysis
- problem isolation
- repair of isolated problem
- verification of proper operation

2.0 IDENTIFICATION OF SYSTEM

The engine control module (ECM) is located in the center of the passenger compartment behind the lower console. The sentry key immobilizer module is located below the steering column behind the steering wheel.

3.0 SYSTEM DESCRIPTION AND FUNCTIONAL OPERATION

3.1 General Description

The 2.5L VM diesel engine system is equipped with the latest in technical advances. The on-board diagnostics incorporated with the engine control module and SKIM are intended to assist the field technician in repairing vehicle problems by the quickest means.

3.2 Functional Operation

3.2.1 ECM On-Board Diagnostics

The ECM has been programmed to monitor many different circuits of the diesel fuel injection system. This monitoring is called "on-board diagnosis".

Certain criteria must be met for a diagnostic trouble code to be entered into the ECM memory. The criteria may be a range of: engine rpm, engine temperature, and/or input voltage to the ECM. If all of the criteria for monitoring a system or circuit are met and a problem is sensed, then a trouble code will be stored in the ECM.

It is possible that a trouble code for a monitored circuit may not be entered into the ECM memory even though a malfunction has occurred. This may happen when the monitoring criteria have not been met.

The ECM compares input signal voltages from each input device with specifications (the established high and low limits of the range) that are programmed into it for that device. If the input voltage is not within specifications and other trouble code criteria are met, a trouble code will be stored in the ECM memory.

3.2.2 ECM Operating Modes

As input signals to the engine control module (ECM) change, the ECM adjusts its response to output devices. For example, the ECM must calculate a different fuel quantity and fuel timing for idle than it does for wide open throttle. There are several different modes of operation that determine how the ECM responds to the various input signals.

Ignition Switch On (Engine Off Mode)

When the ignition switch activates the fuel injection system, the following actions occur:

- 1. The ECM determines atmospheric air pressure from the atmospheric pressure sensor located in the ECM.
- 2. The ECM energizes the fuel quantity actuator and the fuel shudown solenoid if no faults are present.

If the engine is not started within 5 seconds of ignition on, the ECM deactivates the fuel quantity actuator and the fuel shutdown solenoid to prevent overheating.

Engine Start-Up Mode -The ECM uses the engine temperature sensor, fuel temperature sensor, atmospheric pressure sensor, boost pressure sensor and the engine speed sensor to determine fuel delivery during this mode.

Normal Driving Modes - Engine idle, warm-up, acceleration, deceleration and wide open throttle modes are all controlled based on the sensor inputs to the ECM and are modified based on engine temperature, boost pressure and engine speed.

Overheat Protection Mode - If engine temperature becomes too hot, the ECM activates high speed radiator fan operation and limits fuel quantity for engine protection.

Limp-In Modes - The ECM operates in limp-in mode when certain system faults are detected. The ECM operates in one of the following modes based on the severity of the fault:

- 1. 10% torque reduction.
- 2. 50% torque reduction.
- 3. Engine speed limited to 1100 rpm.

After-Run - When fused ignition switch output is removed from the ECM cavity 47, the ECM performs a self-diagnostic check in the following order:

- 1. Electrical shut-off test
- 2. Fuel quantity actuator test
- 3. Monitoring module test
- 4. Voltage regulator test
- 5. Main relay test (if tests 1-4 pass)

If any of tests 1-4 fail, the fault is stored in memory, and can be retrieved during the next ignition cycle using the DRB.

3.2.3 Monitored Circuits

The ECM is able to monitor and identify most driveability related trouble conditions. Some circuits are directly monitored through ECM feedback circuitry. In addition, the ECM monitors the voltage state of some circuits and compares those states with expected values. Other systems are monitored indirectly when the ECM conducts a rationality test to identify problems.

Although most subsystems of the powertrain control module are either directly or indirectly monitored, there may be occasions when diagnostic trouble codes are not immediately identified. For a trouble code to set, specific conditions must be met and unless these conditions are encountered, a code will not set.

3.2.4 SKIS On-Board Diagnostics

The SKIS module has been programmed to transmit and monitor many different coded messages as well as CCD Bus messages. This monitoring is called "On-Board Diagnosis".

Certain criteria must be met for a diagnostic trouble code to be entered into the Sentry Key Immobilizer Module (SKIM) memory. The criteria may be a range of: input voltage, CCD Bus messages, or coded messages to the SKIM. If all of the criteria for monitoring a circuit or function are met and a fault is sensed, a diagnostic trouble code will be stored in the SKIM memory.

3.2.5 SKIS Overview

The Sentry Key Immobilizer System (SKIS) is an immobilizer system designed to prevent unauthorized vehicle operation. The system consists of a Sentry Key Immobilizer Module (SKIM), ignition key(s) equipped with a transponder chip, engine controller and body controller. When the ignition switch is turned on, the SKIM interrogates the ignition key. If the ignition key is "Valid" the SKIM sends a CCD Bus message to the body controller indicating the presence of a valid ignition key. The BCM then supplies the ECM with a valid immobilizer signal allowing the engine to continue to operate.

3.2.6 SKIS Operation

When ignition power is supplied to the SKIM, the SKIM performs an internal self-test. After the self-test is completed, the SKIM energizes the antenna (this activates the transponder chip) and sends a challenge to the transponder chip. The transponder chip responds to the challenge by generating an encrypted response message using the following:

Secret Key – This is an electronically stored value (identification number) that is unique to each SKIS. The secret key is stored in the SKIM, BCM and all ignition key transponders.

Challenge – This is a random number that is generated by the SKIM at each ignition key cycle.

The secret key and challenge are plugged into an algorithm that produces the encrypted response message. The transponder uses the crypto algorithm to receive, decode and respond to the message sent by SKIM. After responding to the coded message, the transponder sends a transponder I.D. message to the SKIM. The SKIM compares the transponder I.D. to the available valid key codes in SKIM memory (8 key maximum). After validating the key the SKIM sends a CCD Bus message called a "Seed Request" to the body controller then waits for a body controller response. If the body controller does not respond, the SKIM will send the seed request again. After three failed attempts the SKIM will stop sending the seed request and store a trouble code. If the body controller sends a seed response, the SKIM sends a valid/invalid key message to the body controller. This is an encrypted message that is generated using the following:

VIN – Vehicle Identification Number

Seed – This is a random number that is generated by the BCM at each ignition key cycle.

The VIN and seed are plugged into a rolling code algorithm that encrypts the "valid/invalid key" message. The body controller uses the rolling code algorithm to receive, decode and respond to the valid/invalid key message sent by SKIM. After sending the valid/invalid key message the SKIM waits 3.5 seconds for an PCM status message from the body controller. If the BCM does not respond with a valid key message to the SKIM, a fault is detected and a trouble code stored.

The SKIS incorporates a warning ("ALARM SET") lamp located in the message center. The lamp receives switched ignition voltage and is hardwired to the body controller. The lamp is actuated when the SKIM sends a CCD Bus message to the body controller requesting the lamp on. The body controller then provides the ground for the lamp. The SKIM will request lamp operation for the following:

- bulb check at ignition on
- to alert the vehicle operator to a SKIS malfunction

For all faults except transponder faults and VIN mismatch, the lamp remains on steady. In the event of a transponder fault the light flashes at the rate of 1Hz (once per second). If a fault is present the lamp will remain on or flashing for the complete ignition cycle. If a fault is stored in SKIM memory which prevents the system from operating properly, the ECM will allow the engine to start and run (for 2 seconds) up to six times. After the sixth attempt, the ECM disables the starter relay until the fault is corrected..

3.3 Diagnostic Trouble Codes

Each diagnostic trouble code is diagnosed by following a specific testing procedure. The diagnostic test procedures contain step-by-step instructions for determining the cause of trouble codes as well as no trouble code problems. It is not necessary to perform all of the tests in this book to diagnose an individual code.

Always begin by reading the diagnostic trouble codes using the DRB. This procedure begins in the DTC TEST - Checking the System for Diagnostic Trouble Codes. This will direct you to the specific test(s) that must be performed.

3.3.1 Hard Code

A diagnostic trouble code that comes back within one cycle of the ignition key is a "hard" code. This means that the defect is there every time the engine control module/SKIM checks that circuit or function. Procedures in this manual verify if the trouble code is a hard code at the beginning of each test. When it is not a hard code, an "intermittent" test must be performed.

3.3.2 Intermittent Code

A diagnostic trouble code that is not there every time the engine control module/SKIM checks the circuit is an "intermittent" code. Most intermittent codes are caused by wiring or connector problems. Defects that come and go like this are the most difficult to diagnose; they must be looked for under specific conditions that cause them. The following checks may assist you in identifying a possible intermittent problem:

- Visually inspect related wire harness connectors. Look for broken, bent, pushed out, or corroded terminals.
- Visually inspect the related harnesses. Look for chafed, pierced, or partially broken wire.
- Refer to any hotlines or technical service bulletins that may apply.

NOTE: Electromagnetic (radio) interference can cause an intermittent system malfunction. This interference can interrupt communication between the ignition key transponder and the SKIM.

3.3.3 Reset Counter

The reset counter counts the number of times the vehicle has been started since codes were last set, erased, or the battery was disconnected. The reset counter will count up to 255 start counts. The number of starts helps determine when the trouble code actually happened. This is recorded by the ECM and can be viewed on the DRB as the RESET COUNTER.

When there are no trouble codes stored in memory, the DRB will display "NO TROUBLE CODES FOUND" and the reset counter will show "RESET COUNT = XXX."

3.3.4 ECM Diagnostic Trouble Codes

A/C CONTROL SHORT CIRCUIT

A/C CONTROL OPEN CIRCUIT

A/C SYSTEM PRESSURE SIGNAL HIGH EXCEEDED

A/C SYSTEM PRESSURE SIGNAL LOW EXCEEDED

A/C SYSTEM PRESSURE SUPPLY HIGH EXCEEDED

A/C SYSTEM PRESSURE SUPPLY LOW EXCEEDED

ACCELERATOR PEDAL SENSOR SIGNAL HIGH EXCEEDED

ACCELERATOR PEDAL SENSOR PLAUSIBILITY

ACCELERATOR PEDAL SENSOR PWG PLAUS WITH LOW IDLE SWITCH

ACCELERATOR PEDAL SENSOR PWG PLAUS WITH POTENTIOMETER

ATMOSPHERIC PRESSURE SENSOR SRC HIGH EXCEEDED

ATMOSPHERIC PRESSURE SENSOR SRC LOW EXCEEDED

BATTERY VOLTAGE SRC HIGH EXCEEDED

BRAKE SIGNAL PLAUS WITH REDUNDANT CONTACT

CLUTCH SIGNAL PLAUSIBILITY

CONTROL SLEEVE SENSOR SIGNAL HIGH EXCEEDED

CONTROL SLEEVE SENSOR START END POS. NOT ATTAINED

CONTROL SLEEVE SENSOR STOP END POS. NOT ATTAINED

CRUISE STATUS INDICATOR LAMP SHORT CIRCUIT

DIAGNOSTIC LAMP OPEN CIRCUIT

DIAGNOSTIC LAMP SHORT CIRCUIT

DIESEL POWER RELAY SHUTS OFF TOO EARLY

DIESEL POWER RELAY SHUTS OFF TOO LATE

EEPROM PLAUSIBILITY CHECKSUM ERROR FOR ADJ. (EGR)

EEPROM PLAUSIBILITY CHECKSUM ERROR IN CC212

EEPROM PLAUSIBILITY COMMUNICATION WITH EEPROM

EEPROM PLAUSIBILITY FUNC. SWITCH WRONG OR MISSING

EEPROM PLAUSIBILITY VER. NUMBER NOT CORRESPONDING

EGR OPEN CIRCUIT Ε EGR SHORT CIRCUIT N ENGINE SPEED SENSOR DYNAMIC PLAUSIBILITY Ε ENGINE SPEED SENSOR OVER SPEED RECOGNITION R ENGINE SPEED SENSOR STATIC PLAUSIBILITY Α FAN CONTROL OPEN CIRCUIT FAN#1 FAN CONTROL OPEN CIRCUIT FAN #2 FAN CONTROL SHORT CIRCUIT FAN #1 ı FAN CONTROL SHORT CIRCUIT FAN #2 FUEL QUANTITY ACTUATOR NEG. GOV. DEVIATION COLD N F FUEL QUANTITY ACTUATOR NEG. GOV. DEVIATION WARM FUEL QUANTITY ACTUATOR POS. GOV. DEVIATION COLD 0 R FUEL QUANTITY ACTUATOR POS. GOV. DEVIATION WARM M FUEL TEMPERATURE SENSOR SRC HIGH EXCEEDED FUEL TEMPERATURE SENSOR SRC LOW EXCEEDED Α T GLOW RELAY #1 CONTROLLER OPEN CIRCUIT GLOW RELAY #2 CONTROLLER OPEN CIRCUIT GLOW RELAY #1 CONTROLLER SHORT CIRCUIT 0 GLOW RELAY #2 CONTROLLER SHORT CIRCUIT IMMOBILIZER SIGNAL LOST INVALID SKIM MESSAGE INDUCTIVE AUX. SPEED SENSOR DYNAMIC PLAUSIBILITY INDUCTIVE AUX. SPEED SENSOR OVERSPEED RECOGNITION INDUCTIVE AUX. SPEED SENSOR PLAUSIBILITY INDUCTIVE AUX. SPEED SENSOR STATIC PLAUSIBILITY MICROCONTROLLER GATE-ARRAY MONITORING MICROCONTROLLER GATE-ARRAY WATCHDOG MICROCONTROLLER PREPARE FUEL QUANTITY STOP MICROCONTROLLER RECOVERY HAS OCCURRED MICROCONTROLLER REDUNDANT OVERRUN MONITORING NEEDLE MOVEMENT SENSOR SRC HIGH EXCEEDED NEEDLE MOVEMENT SENSOR SRC LOW EXCEEDED REDUNDANT EMER. STOP PLAUSIBILITY IN AFTER-RUN REDUNDANT EMER. STOP POWERSTAGE DEFECTIVE REGULATOR LOWER REGULATOR LIMIT REGULATOR UPPER LIMIT SOLENOID VALVE CONTROLLER OPEN CIRCUIT SOLENOID VALVE CONTROLLER SHORT CIRCUIT TEMPERATURE OF ENGINE COOLANT SRC HIGH EXCEEDED TEMPERATURE OF ENGINE COOLANT SRC LOW EXCEEDED TERMINAL #15 PLAUSIBILITY AFTER START-UP TIMING GOVERNING NEGATIVE GOVERNOR DEVIATION TIMING GOVERNING POSITIVE GOVERNOR DEVIATION TURBOCHARGER BOOST SENSOR SIGNAL HIGH EXCEEDED TURBOCHARGER BOOST SENSOR SIGNAL LOW EXCEEDED TURBOCHARGER BOOST SENSOR SUPPLY HIGH EXCEEDED TURBOCHARGER BOOST SENSOR SUPPLY LOW EXCEEDED TURBOCHARGER BOOST SENSOR PLAUSIBILITY

VEHICLE SPEED SENSOR PEC FREQUENCY TOO HIGH VEHICLE SPEED SENSOR SIGNAL SRC HIGH EXCEEDED

VEHICLE SPEED SENSOR PLAUSIBILITY

6

3.3.5 SKIM Diagnostic Trouble Codes

ANTENNA FAILURE
COP FAILURE
EEPROM FAILURE
PCM STATUS FAILURE
INTERNAL FAULT
RAM FAILURE
ROLLING CODE FAILURE
SERIAL LINK EXTERNAL FAULT
STACK OVERFLOW FAILURE
TRANSPONDER COMMUNICATION FAILURE
TRANSPONDER CRC (CYCLIC REDUNDANCY CHECK) FAILURE
TRANSPONDER ID MISMATCH
TRANSPONDER RESPONSE MISMATCH
VIN MISMATCH

3.3.6 Handling No Trouble Code Problems

After reading Section 3.0 (System Description and Functional Operation), you should have a better understanding of the theory and operation of the on-board diagnostics, and how this relates to the diagnosis of a vehicle that may have a driveability-related symptom or complaint.

The "no code" system is broken down into three test methods:

- No Code Complete Test
- No Code Quick Individual Test
- No Code Quick Symptom Test

3.4 Using the DRB

Refer to the DRB user's guide for instructions and assistance with reading trouble codes, erasing trouble codes, and other DRB functions.

3.5 DRB Error Messages and Blank Screen

Under normal operation, the DRB will display one of only two error messages:

User-Requested WARM Boot or User-Requested COLD Boot

This is a sample of such an error message display:

ver: 2.14 date: 26 Jul93 file: key_itf.cc date: Jul 26 1993

line 548 err: 0x1

User-Requested COLD Boot

Press MORE to switch between this display

and the application screen.

Press F4 when done noting information.

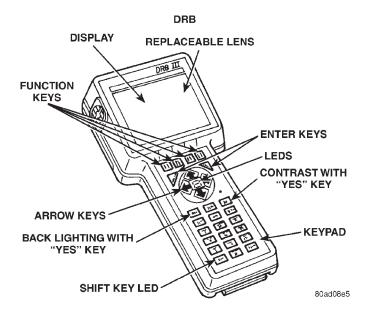
3.5.1 DRB Does Not Power Up

If the LED's do not light or no sound is emitted at start up, check for loose cable connections or a bad cable. Check the vehicle battery voltage (data link connector cavity 16). A minimum of 11 volts at DLC cavity 16 is required to adequately power the DRB. Check for proper ground connection at DLC cavities 4 and 5.

If all connections are proper between the DRB and the vehicle or other devices, and the vehicle battery is fully charged, an inoperative DRB may be the result of faulty cable or vehicle wiring. For a blank screen, refer to the appropriate diagnostics manual.

3.5.2 Display is Not Visible

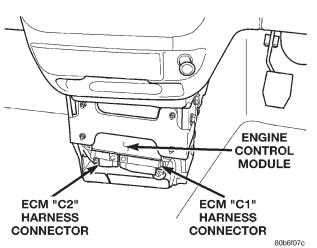
Low temperatures will affect the visibility of the display. Adjust the contrast to compensate for this condition.

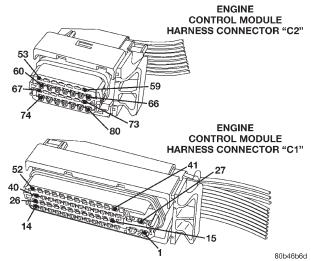


4.0 SYSTEM COMPONENT LOCATIONS

4.1 Engine Control Module

2.5L

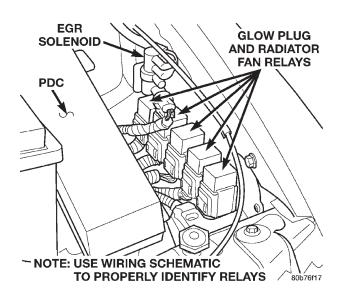


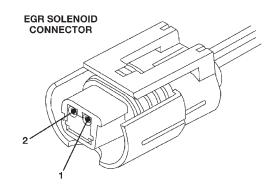


CAV CKT/COLOR		FUNCTION	
1	Z12 BK/TN	Ground	
2	A142 DG/OR	Diesel Power Relay Output	
3	K90 TN	Starter Relay Control	
5	C13 DB/OR	A/C Compressor Clutch Control	
6	K159 VT/RD	Engine Speed Sensor Signal	
		Output	
8	C103 DG/LB	A/C Switch Signal	
9	K29 WT/PK	Secondary Brake Switch Signal	
11	K6 VT/WT	5-Volt Supply	
12	K151 WT	Low Idle Position Switch Sense	
13	K21 BK/RD	Intake Air Temperature Sensor Signal	
17	C24 DB/PK	Low Speed Fan Control	
20	L50 WT/TN	Primary Brake Switch Signal	
23	K167 BR/YL	Accelerator Pedal Position Sensor Ground	
24	K22 OR/DB	Accelerator Pedal Position Sensor Signal	
27	Z12 BK/TN	Ground	
28	A142 DG/OR	Diesel Power Relay Output	
29	K35 GY/YL	EGR Solenoid Control	
30	V38 LB/RD	Speed Control Lamp Control	
33	K51 DB/YL	Diesel Power Relay Control	
34	G385 OR/PK	Diagnostic/Glow Plug Lamp Control	
38	G56 OR/BK	Immobilizer Signal	
39	K9 LB	5-Volt Supply	
40	K1 DG/RD	Boost Pressure Sensor Signal	
41	C137 YL	High Speed Fan Control	
41	C137 YL	High Speed Fan Control	

CAV CKT/COLOR		FUNCTION	
42	K152 WT/DG	Glow Plug Relay #1 Control	
43	K252 LG/OR	Glow Plug Relay #2 Control	
45	D21 PK	ISO K-line	
46	K119 LG/BK	Clutch Pedal Switch Signal	
47	F87 WT/BK	Ignition Switch Supply	
50	K7 OR	5-Volt Supply	
51	G7 WT/OR	Vehicle Speed Sensor Signal	
52	C18 DB	A/C Pressure Sensor Signal	
53	K156 GY	Fuel Temperature Sensor Signal	
54	K2 TN/BK	Engine Coolant Temperature Sensor Signal	
55	K68 LG/YL	Needle Movement Sensor Ground	
56	K134 LB/BK	Control Sleeve Position Sensor Signal	
57	K57 LG/OR	Middle Tap	
58	K135 WT/BK	Measure Coil	
59	K140TN/WT	Fuel Quantity Actuator Control	
60	V37 RD/LG	Speed Control Switch Signal	
61	61 K4 BK/LB Sensor Ground		
62	K67 BR/BL	Neddle Movement Sensor Signal	
66	K140 TN/WT	Fuel Quantity Actuator Control	
67	K24 GY/BK	Engine Speed Sensor Signal	
69	K3 BK/VT	Engine Speed Sensor Ground	
77	K153 OR/DG	Fuel Shutdown Solenoid Control	
79	K126 LG	Fuel Timing Solenoid Control	
80	K140 TN/WT	Fuel Quantity Actuator Control	

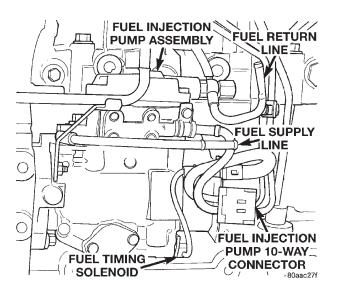
4.2 Controls and Solenoids

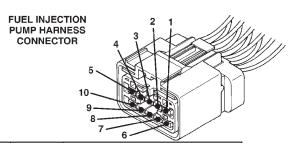




CAV	COLOR	FUNCTION
1 2	DG/OR GY/YL	DIESEL POWER RELAY OUTPUT EGR SOLENOID CONTROL

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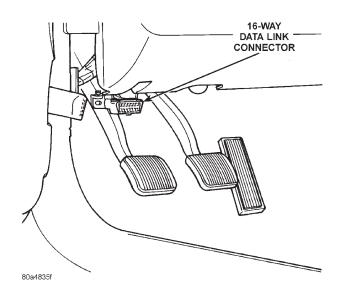


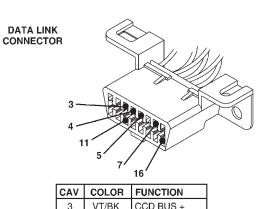


CAV	COLOR	FUNCTION
1	LB/BK	Control Sleeve Position Sensor Signal
2	LG/OR	Middle Tap
3	WT/BK	Measure Coil
4	BK/LB	Fuel Temperature Sensor Ground
5	LG	Fuel Timing Solenoid Control
6	OR	Fuel Shutdown Solenoid Control
7	GY	Fuel Temperature Sensor Signal
8	TN/WT	Fuel Quantity Actuator Control
9	DG/OR	Diesel Power Relay Output
10	DG/OR	Diesel Power Relay Output

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4.3 <u>Data Link Connector</u>



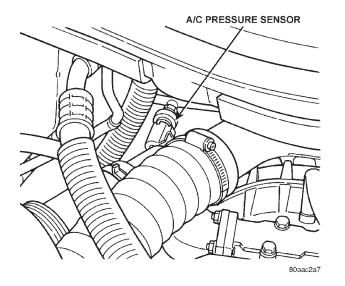


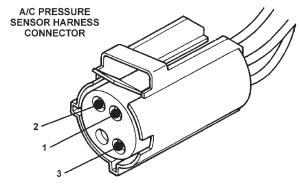
ÇAV	COLOR	FUNCTION
3	VT/BK	CCD BUS +
4	BK/LG	GROUND
5	BK/WT	GROUND
7	PK	ISO K-LINE
11	WT/BK	CCD BUS -
l 16	l PK	FUSED (B+)

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O N

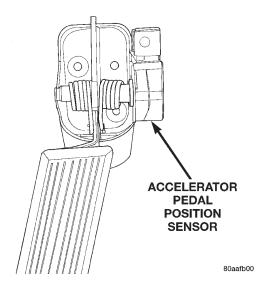
4.4 Sensors

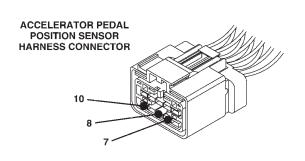




CAV	COLOR	FUNCTION
1	BK/LB	SENSOR GROUND
2	OR	5-VOLT SUPPLY
3	DB	A/C PRESSURE SENSOR SIGNAL

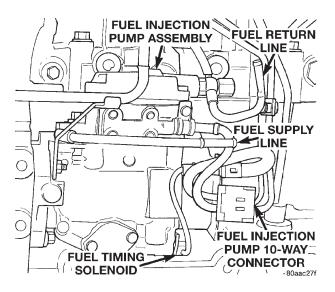
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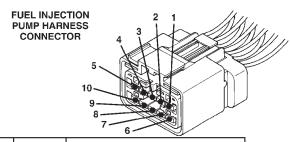




CAV	COLOR	FUNCTION
7	OR/DB	ACCEL PEDAL POSITION SENSOR SIGNAL
8	BR/YL	SENSOR GROUND
10	VT/WT	5-VOLT SUPPLY

80aa4b8b

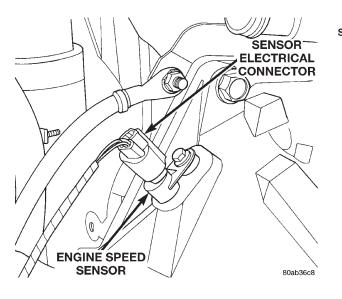


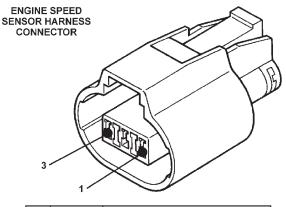


CAV	COLOR	FUNCTION
1	LB/BK	Control Sleeve Position Sensor Signal
2	LG/OR	Middle Tap
3	WT/BK	Measure Coil
4	BK/LB	Fuel Temperature Sensor Ground
5	LG	Fuel Timing Solenoid Control
6	OR	Fuel Shutdown Solenoid Control
7	GY	Fuel Temperature Sensor Signal
8	TN/WT	Fuel Quantity Actuator Control
9	DG/OR	Diesel Power Relay Output
10	DG/OR	Diesel Power Relay Output

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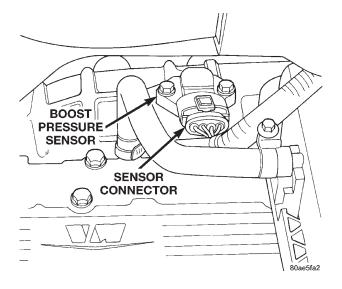
4.4 Sensors (Continued)

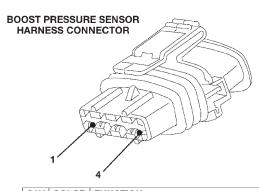




CAV	COLOR	FUNCTION
1 3	BK/LB GY/BK	SENSOR GROUND ENGINE SPEED SENSOR SIGNAL

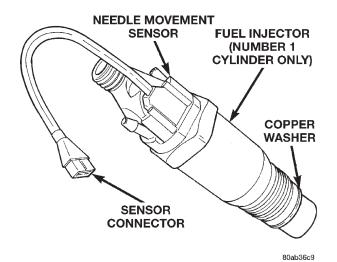
80aa4b86

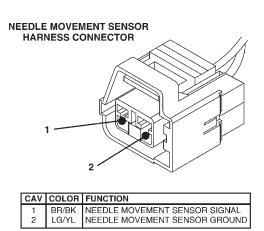




CAV	COLOR	FUNCTION
1	BK/LB	SENSOR GROUND
2	BK/RD	IAT SENSOR SIGNAL
3		5-VOLT SUPPLY
4	DG/RD	BOOST PRESSURE SENSOR SIGNAL

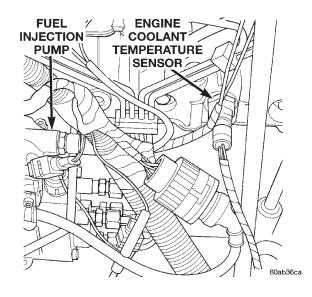
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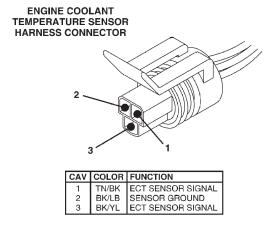




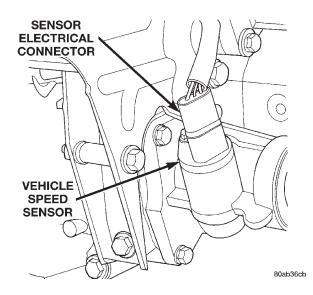
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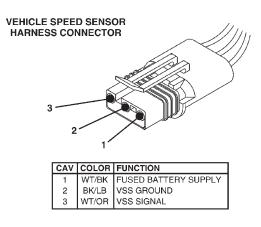
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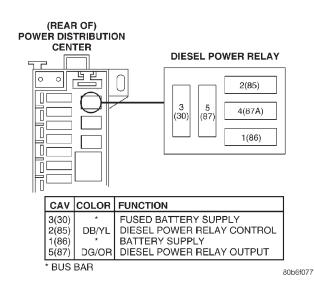
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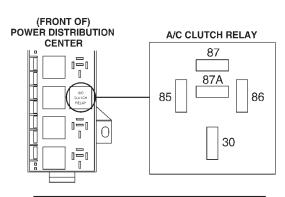




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4.6 Relays





CAV	COLOR	FUNCTION
30	*	FUSED BATTERY SUPPLY
85	DB/OR	A/C COMP CLUTCH RELAY CONTROL
86	DG/QR	DIESEL POWER RELAY OUTPUT A/C COMP CLUTCH RELAY OUTPUT
87	DB/BK	A/C COMP CLUTCH RELAY OUTPUT

* BUS BAR

Chrysler Engine Control Module And Sentry Key Immobilizer System

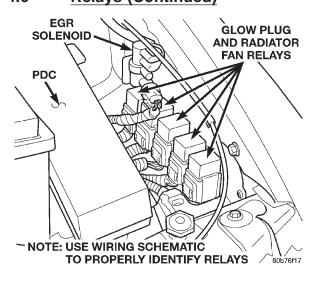
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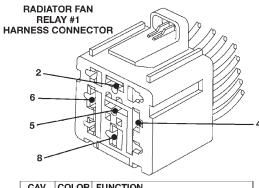
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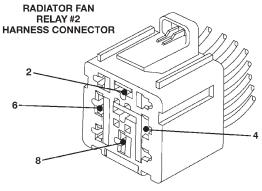
Full download: http://manualplace.com/download/chrysler-engine-control-module-and-sentry-key-immobilizer-system/





FUNCTION
GROUND
DIESEL POWER RELAY OUTPUT
FAN SUPPLY
HIGH SPEED FAN CONTROL
GROUND

80b76e6e



CAV	COLOR	FUNCTION
2 (87)		FAN RELAY #2 OUTPUT
4 (86)	DG/QR	DIESEL POWER RELAY OUTPUT
6 (85)	DB/PK	LOW SPEED FAN CONTROL
8 (30)	GY	BATTERY SUPPLY

CAV COLOR FUNCTION

2 (87) DB/PK FAN RELAY #3 OUTPUT
4 (86) DG/OR DIESEL POWER RELAY OUTPUT

8 (30) RD/BK BATTERY SUPPLY

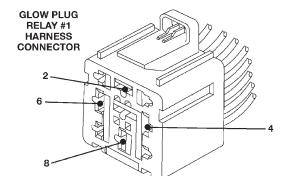
RADIATOR FAN

RELAY #3

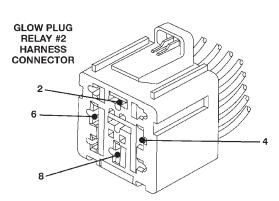
HARNESS CONNECTOR

6 (85)

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CAV	COLOR	FUNCTION
2 (87)	GY	GLOW PLUG RELAY #1 OUTPUT
4 (86)	WT	GLOW PLUG RELAY #1 CONTROL
6 (85)	DG/OR	DIESEL POWER RELAY OUTPUT
8 (30)	RD	GLOW PLUG RELAY #1 OUTPUT GLOW PLUG RELAY #1 CONTROL DIESEL POWER RELAY OUTPUT FUSED B (+)



HIGH SPEED FAN CONTROL

CAV	COLOR	FUNCTION
2 (87)	GY	GLOW PLUG RELAY #2 OUTPUT
4 (86)	WT	GLOW PLUG RELAY #2 CONTROL
6 (85)	DG/OR	DIESEL POWER RELAY OUTPUT
8 (30)	RD	FUSED B (+)

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